# Noise-Dependent Stability of the Synchronized State in a Coupled System of Active Rotators

Sebastian F. Brandt<sup>1</sup>, Axel Pelster<sup>2</sup>, and Ralf Wessel<sup>1</sup>

<sup>1</sup>Department of Physics, Washington University in St. Louis <sup>2</sup>Fachbereich Physik, Universität Duisburg-Essen, Campus Duisburg





#### arXiv: 0802.1105

Phase Dynamics of Excitable Systems

• Kuramoto Model for active rotators

 $\dot{\phi}(t) = \omega - a\sin\phi(t)$ 

- Langevin Equation  $\dot{\phi}_i(t) = \omega - a \sin \phi_i(t) - \sum_{j=1}^n W_{ij}(\phi_j - \phi_i) + \eta_i(t)$   $W_{ij}(\phi) = w_{ij} \sin \phi$  $\langle \eta_i(t) \rangle = 0, \qquad \langle \eta_i(t_1)\eta_j(t_2) \rangle = 2\sigma \delta(t_1 - t_2)\delta_{ij}$
- Fokker-Planck Equation

$$\frac{\partial}{\partial t}P(\phi,t) = -\sum_{i=1}^{n} \frac{\partial}{\partial \phi_i} \left[ D_i(\phi)P(\phi,t) \right] + \sum_{i=1}^{n} \sum_{j=1}^{n} \frac{\partial^2}{\partial \phi_i \partial \phi_j} \left[ D_{ij}(\phi)P(\phi,t) \right]$$
$$D_i(\phi) = \omega - a \sin \phi_i - \sum_{j=1}^{n} w_{ij} \sin(\phi_j - \phi_i), \qquad D_{ij}(\phi) = \delta_{ij}\sigma$$

# Single Rotator

• Fokker-Planck Equation

$$\frac{\partial}{\partial t}P(\phi,t) = -\frac{\partial}{\partial \phi}\left[D(\phi)P(\phi,t)\right] + \sigma \frac{\partial^2}{\partial \phi^2}P(\phi,t)$$

- Potential  $D(\phi) = \omega - a \sin \phi$ ,  $V(\phi) = -\omega \phi - a \cos \phi + c$
- Probability Current  $S(\phi, t) = D(\phi)P(\phi, t) - \sigma \frac{\partial}{\partial \phi}P(\phi, t)$
- Continuity Equation

$$\frac{\partial}{\partial t}P(\phi,t) + \frac{\partial}{\partial \phi}S(\phi,t) = 0$$

**General Stationary Solution** 

• Constant Probability Current  $\rightarrow$  Solution

$$P(\phi) = Ce^{-\frac{V(\phi)}{\sigma}} - \frac{S}{\sigma} \int_0^{\phi} d\phi' e^{\frac{V(\phi') - V(\phi)}{\sigma}}$$

• Determine Constants through Normalization and Boundary Conditions

$$C = \frac{e^{-\frac{V(2\pi)}{\sigma}}}{\det} \int_0^{2\pi} d\phi \ e^{\frac{V(\phi)}{\sigma}}, \quad S = \frac{\sigma}{\det} \left[ e^{-\frac{V(2\pi)}{\sigma}} - e^{-\frac{V(0)}{\sigma}} \right]$$

$$\det = \begin{vmatrix} \int_0^{2\pi} d\phi \, e^{-\frac{V(\phi)}{\sigma}} & \int_0^{2\pi} d\phi \int_0^{\phi} d\phi' e^{\frac{V(\phi') - V(\phi)}{\sigma}} \\ e^{-\frac{V(2\pi)}{\sigma}} - e^{-\frac{V(0)}{\sigma}} & \int_0^{2\pi} d\phi \, e^{\frac{V(\phi) - V(2\pi)}{\sigma}} \end{vmatrix}$$

## Mean Frequency of Active Rotator

• Integral Representation

$$\bar{\omega} = 2\pi S = \frac{2\pi\sigma \left(1 - e^{-\frac{2\pi\omega}{\sigma}}\right)}{\int_0^{2\pi} d\phi' \, e^{-\frac{\omega}{\sigma}\phi'} \int_0^{2\pi} d\phi \, e^{\frac{a}{\sigma}\left[\cos(\phi + \phi') - \cos\phi\right]}}$$

1

• Large-Noise Limit

 $\lim \,\bar{\omega} = \omega$  $\sigma \rightarrow \infty$ 

• Small-Noise Limit

$$\bar{\omega}_{asy} = \sqrt{a^2 - \omega^2} e^{-\frac{2}{\sigma} \left(\sqrt{a^2 - \omega^2} - \omega \arccos \frac{\omega}{a}\right)}$$



Analytical and Numerical Results

### Deterministic Two-Rotator System

• Dynamical System:  $\Phi = \frac{\phi_1 + \phi_2}{2}, \quad \Delta = \frac{\phi_1 - \phi_2}{2}$  $\dot{\Phi}(t) = \omega - a \sin \Phi(t) \cos \Delta(t) + (w_{12} - w_{21}) \sin \Delta(t) \cos \Delta(t),$ 

 $\dot{\Delta}(t) = -a\cos\Phi(t)\sin\Delta(t) + (w_{12} + w_{21})\sin\Delta(t)\cos\Delta(t).$ 

- Fixed Point  $\Phi(t) = \Phi_0 = \sin^{-1}(\omega/a), \qquad \Delta(t) = 0$
- Eigenvalues of Stability Matrix  $\lambda_1 = -\sqrt{a^2 - \omega^2}, \qquad \lambda_2 = w_{12} + w_{21} - \sqrt{a^2 - \omega^2}$
- Subcritical Pitchfork Bifurcation

$$w_{12} + w_{21} = \sqrt{a^2 - \omega^2}$$

### **Bifurcation Diagram**

• Coexistence of Stable Fixed Point and Oscillations



 $w_{12} = w_{21} = w$ ,  $\omega = 1$ , a = 1.2

#### Stochastic Two-Rotator System

Stationary Solution to Fokker-Planck Equation





### Analytical and Numerical Results



## Fourier Expansion

• Ansatz

$$P(\phi_1, \phi_2) = \sum_{k_1, k_2} C(k_1, k_2) e^{i(k_1\phi_1 + k_2\phi_2)}$$

• Infinite System of Algebraic Equations

$$\begin{split} 0 &= \sum_{k_1,k_2} e^{i(k_1\phi_1 + k_2\phi_2)} \sum_{|l_1| < 1, |l_2| < 1} C(k_1 - l_1, k_2 - l_2) \tilde{C}(l_1, k_1 - l_1, l_2, k_2 - l_2) \\ \tilde{C}(\pm 1, k_1, 0, k_2) &= \frac{a}{2} (1 \pm k_1) \\ \tilde{C}(0, k_1, \pm 1, k_2) &= \frac{a}{2} (1 \pm k_2) \\ \tilde{C}(1, k_1, -1, k_2) &= -\frac{1 + k_1}{2} w_{12} - \frac{1 - k_2}{2} w_{21} \\ \tilde{C}(-1, k_1, 1, k_2) &= -\frac{1 - k_1}{2} w_{12} - \frac{1 + k_2}{2} w_{21} \\ \tilde{C}(\pm 1, k_1, \pm 1, k_2) &= 0 \end{split}$$

### First-Order Expansion Result

• Probability Density

 $P_1(\phi_1,\phi_2) = \frac{1}{4\pi^2} + \alpha \{ 2a\beta\gamma\sigma(\cos\phi_1 + \cos\phi_2) + 4a\beta\sigma\omega(\sin\phi_1 + \sin\phi_2) + (a^2\gamma\sigma^2 - 2a^2\sigma\omega^2) \\ \times \cos(\phi_1 + \phi_2) + [a^2\beta\gamma - w\beta(\gamma^2 + 4\omega^2)]\cos(\phi_1 - \phi_2) + a^2\sigma(w\omega + 4\sigma\omega)\sin(\phi_1 + \phi_2) \}$ 

• Marginal Probability Density

$$\bar{P}_1(\Delta) = \frac{1}{2\pi} + 2\pi\alpha\beta(a^2\gamma - w\gamma^2 - 4w\omega^2)\cos(2\Delta)$$

• Phase Transition

$$\sigma = \frac{a^2 - 2w^2 \pm \sqrt{a^4 - 16w^2\omega^2}}{4w}$$